Recommended for Further Reading

Pauli Matrices

A Summer Course given at University of Hyderabad

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Contents

We summarize some important properties of Pauli Matrices.

1. The three Pauli matrices are given by

$$\sigma_1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \qquad \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \qquad \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \tag{1}$$

2. The Pauli matrices satisfy the commutation relations.

$$[\sigma_i, \sigma_j] = 2i\epsilon_{ijk}\sigma_k \tag{2}$$

3. The square of each Pauli matrix is unity. So is the square of $\hat{n} \cdot \vec{\sigma}$ where \hat{n} is a unit vector.

$$\sigma_1^2 = \sigma_2^2 = \sigma_3^2 = \hat{I}; \qquad \hat{n} \cdot \vec{\sigma}^2 = \hat{I}$$
 (3)

- 4. Every Pauli matrix anticommutes with the other two Pauli matrices. There does not exist a nonzero 2 × 2 matrix which anticommutes with all the three Pauli matrices.
- 5. The above relations can be written in various different forms.

$$[\sigma_i, \sigma_j] = 2i\epsilon_{ijk}\sigma_k \tag{4}$$

$$\sigma_j \sigma_k + \sigma_k \sigma_j = 2\delta_{jk} \tag{5}$$

6. The above two relations imply that

$$\sigma_i \sigma_k = \delta_{ik} + i \epsilon_{ik\ell} \sigma_{\ell} \tag{6}$$

7. The above statements are can be rewritten as

(a)
$$[\vec{a} \cdot \vec{\sigma}, \vec{b} \cdot \vec{\sigma}] = 2i(\vec{a} \times \vec{b}) \cdot \vec{\sigma}$$

(b)
$$(\vec{a} \cdot \vec{\sigma})^2 = |\vec{a}|^2$$

$$(c) \ (\vec{a} \cdot \vec{\sigma})(\vec{b} \cdot \vec{\sigma}) + (\vec{b} \cdot \vec{\sigma})(\vec{a} \cdot \vec{\sigma}) = 2(\vec{a} \cdot \vec{b})\hat{I}$$

$$(d) \ (\vec{a} \cdot \vec{\sigma})(\vec{b} \cdot \vec{\sigma}) = (\vec{a} \cdot \vec{b})\hat{I} + i(\vec{a} \times \vec{b}) \cdot \vec{\sigma}$$

where \vec{a}, \vec{b} are two arbitrary numerical vectors.

8. The trace of each of the three matrices is zero. If we use the notation $\sigma_0 = \hat{I}$ we have the relation, we can write

$$Tr(\sigma_{\mu}\sigma_{\nu}) = 2\delta_{\mu\nu} \tag{7}$$

- 9. The above identity can be used to prove linear independence of Pauli matrices. The four matrices σ_{μ} , $\mu = 0, ..., 3$ form a basis in the complex vector space of all 2×2 matrices.
- 10. Let S be complex 2×2 matrix which is expanded in terms of the matrices σ_{μ}

$$S = \sum_{\mu=0}^{3} C_{\mu} \sigma_{\mu} \tag{8}$$

The expansion coefficients are given by

$$C_{\mu} = \frac{1}{2} Tr(S\sigma_{\mu}) \tag{9}$$

11. The completeness relation for the Pauli matrices is contained in the identity

$$\sum_{a} (\sigma^{a})_{ij} (\sigma^{a})_{kl} = 2\delta_{il}\delta_{jk} - \delta_{ij}\delta_{kl}. \tag{10}$$

12. An important identity satisfied by the Pauli matrices is

$$\exp(i\vec{\alpha}\cdot\vec{\sigma}) = \cos|\vec{\alpha}| + i\vec{\alpha}\cdot\sigma\sin|\vec{\alpha}| \tag{11}$$

where $\vec{\alpha}$ is a vector and

$$(\alpha_1, \alpha_2, \alpha_3), \qquad |\vec{\alpha}| = \sqrt{\alpha_1^2 + \alpha_2^2 + \alpha_2^2}$$
 (12)

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